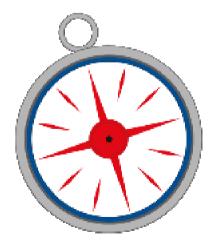
WPVS for Content Analysis of Spatially Enhanced Multimedia

Dr. Eduardo Dias Drs. Arnoud de Boer

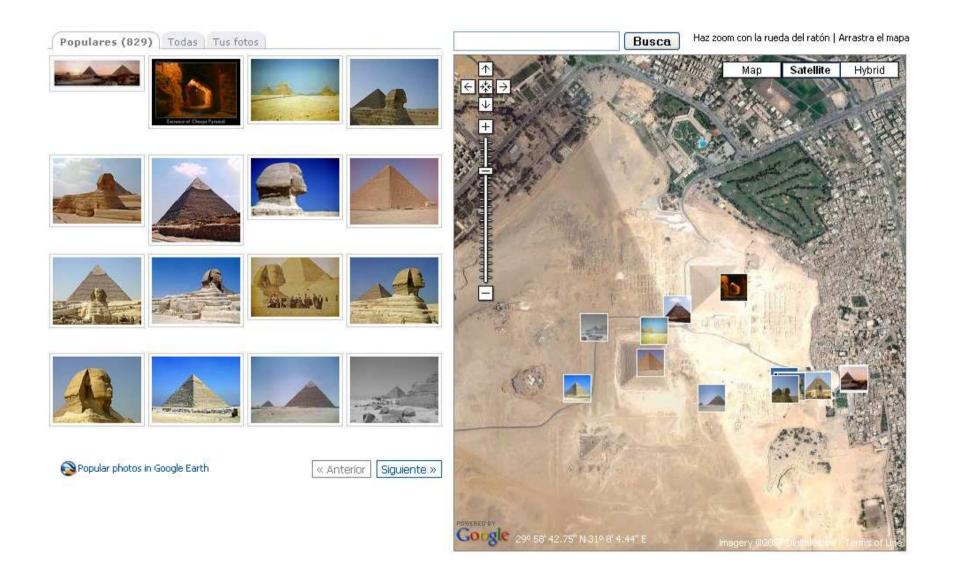
Road map

- Introduction
- Data preparation
- WPVS in action
- Inaccuracies and limitations
- Conclusions



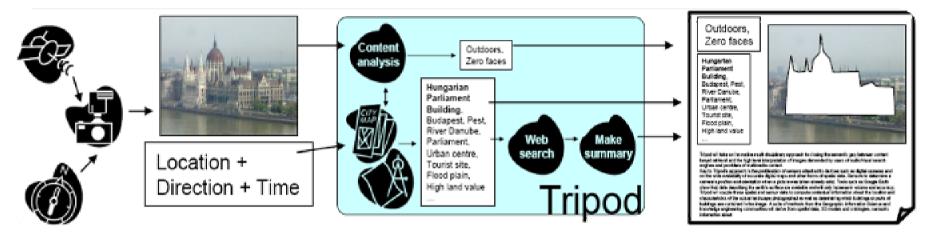
Introduction

- Increasing availability of all-in-one capture devices and online multimedia
- Geotagging: adding location metadata to multimedia
- Photo annotation = captioning + labeling
- Content-based: classification; not identification
- Location metadata = contextual information



"Improve access to enormous body of visual media"

Photo annotation & image retrieval tools Camera with GPS **and** compass captures full spatial metadata

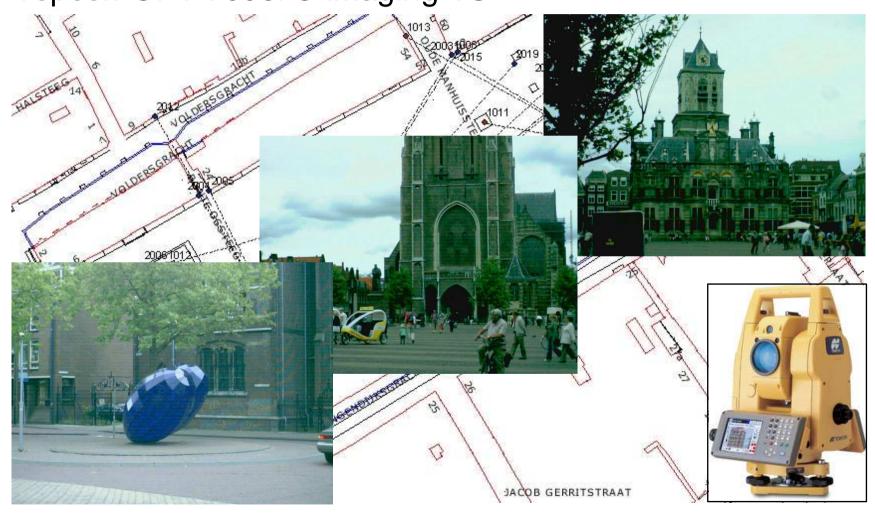


Dias E, de Boer A, Fruijtier S, Oddoye JP, Harding J, Matyas C, Minelli S (2007) Requirements and business case study. Project deliverable D1.2. TRIPOD: TRI-Partite multimedia Object Description. EC-IST Project 045335 (www.projecttripod.org).

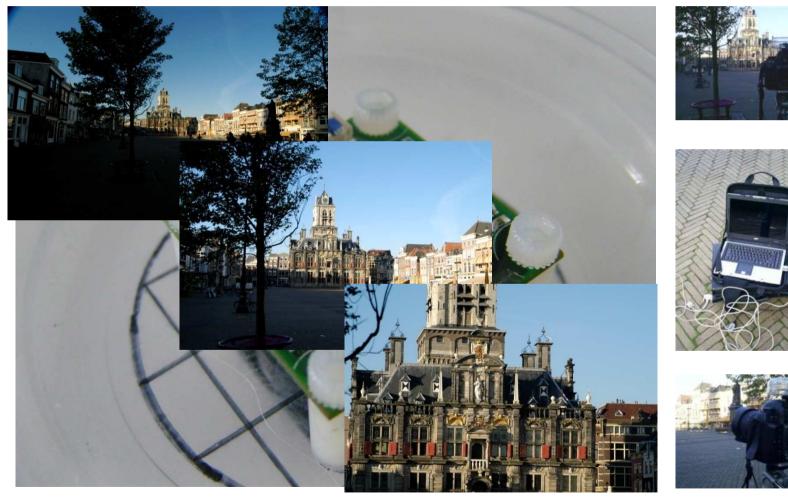


Historic town hall, Delft, The Netherlands

Low-resolution and high spatial accuracy photos Topcon GPT-7003i © imaging TS



High-resolution and low spatial accuracy photos Nikon D-100 © SLR camera with different lenses



Oceanserver 3-axis digital compass

- Specifications:
 - 3-axis compass: heading, pitch, roll
 - 0.1 resolution / 1º accuracy
 - tilt-compensated / calibrated
 - 0.1-20Ghz update rate
 - 1.4" x 1.8" ~ 35 x 40 mm
 - USB en RS232 connectivity





7D Spatial metadata

• 3-axis compass

- Heading, roll, pitch, timestamp

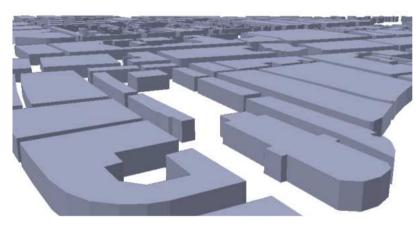
- GPS
 - latitude, longitude, height, timestamp
- Camera

- timestamp (+ focal length, subject distance)

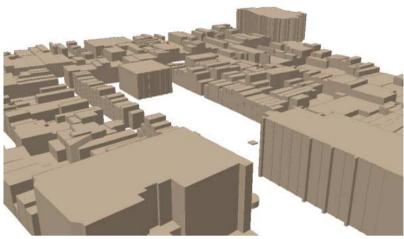


Data collected			
ID	2014		
POI_coord	(84485.89177 447579.9073 10.3164)		
POC_coord	(84409.194 447510.0159 0.6771951)		
Heading	47.66°		
Pitch	4.44°		
Roll	0 °		
Subject distance	104.027 m		
View angle	30°		
Focal Length	8 mm		
Timestamp	8/8/2007 15:04		
Resolution	640x480		
Device	Topcon GPT-7003i		
Sensor	0.3M pixels (VGA) CMOS Sensor		

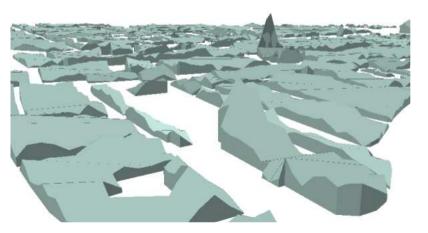
Spatial data preparation Three-dimensional models from 2D footprints and DEM data



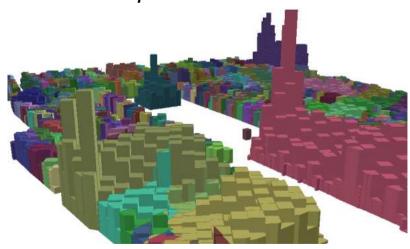
Model 1. Assumed height values



Model 2. Update centroid with AHN

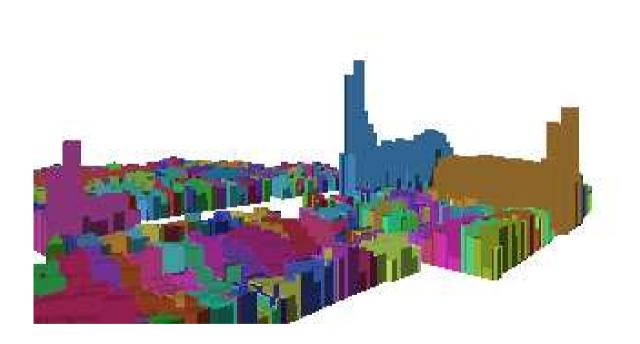


Model 3. AHN for base heights



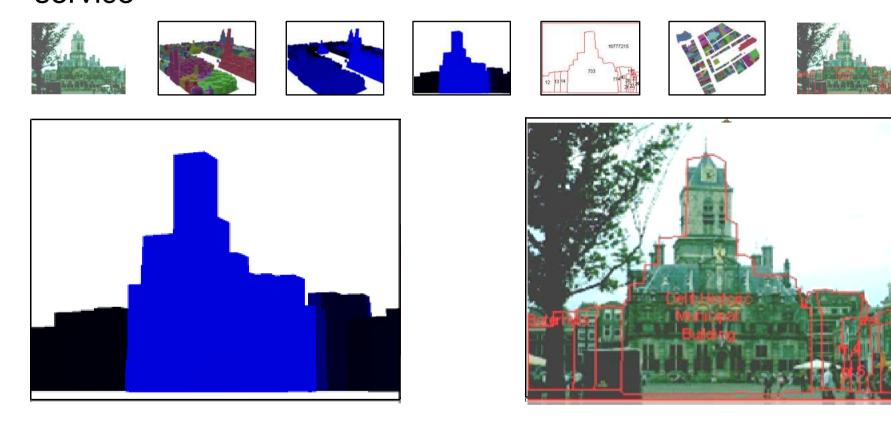
Model 4. Sticks from AHN-to-vector

Extrusion of DEM cells Approximates building shapes



Object identification

Virtual scene from perspective viewer service

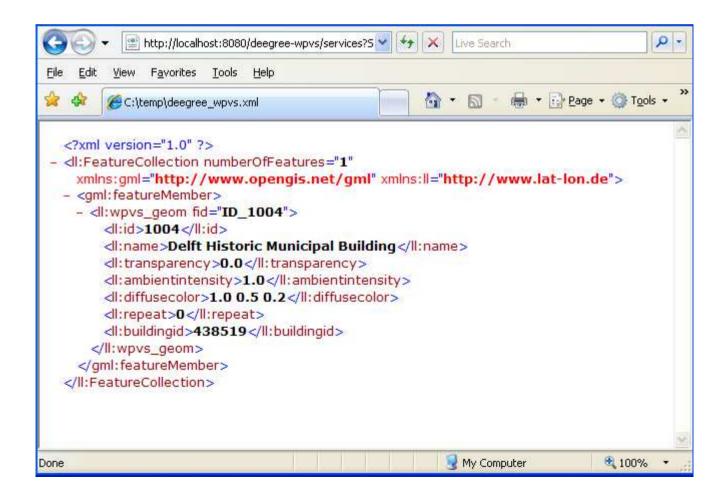


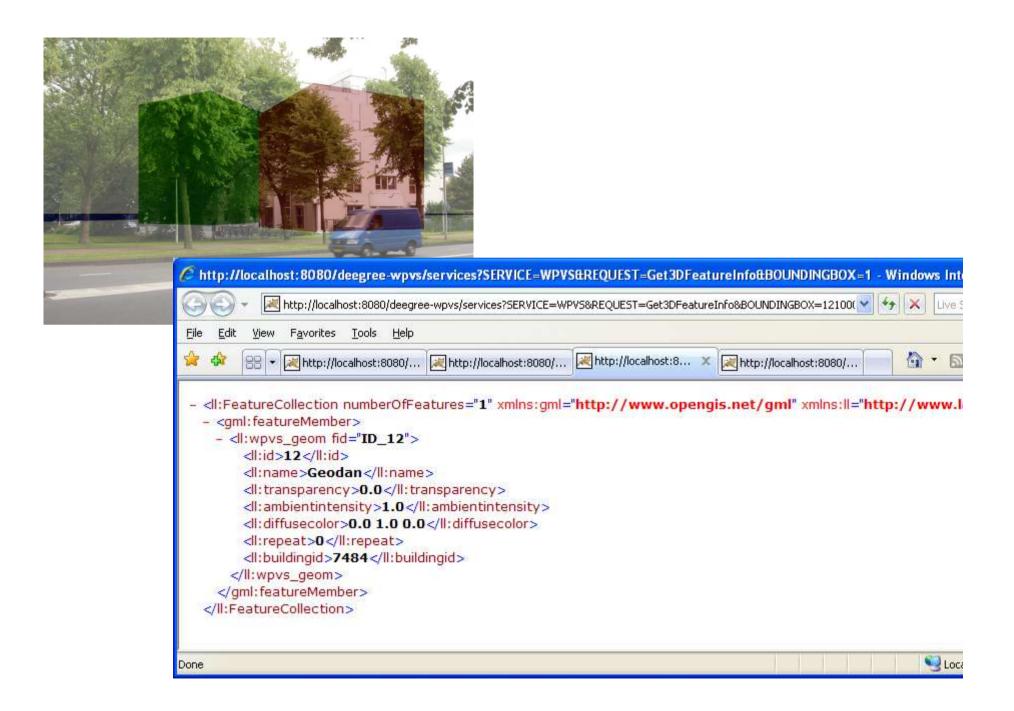
3D analysis / WPVS

Reverse Color engineering

Deegree WPVS offers

Get3DFeatureInfo:





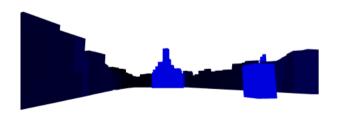
4. Effects of distortions and inaccuracies

Lens distortions and GPS and compass inaccuracies

Lens distortions

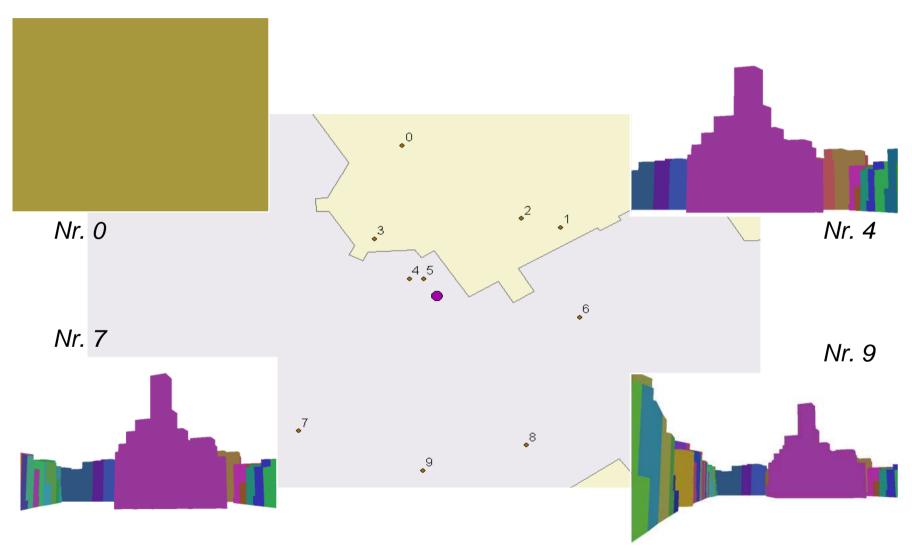
• Barrel and pincushion distortion

No Distortion	Pincushion Distortion	No Distortion	Barrel Distortion



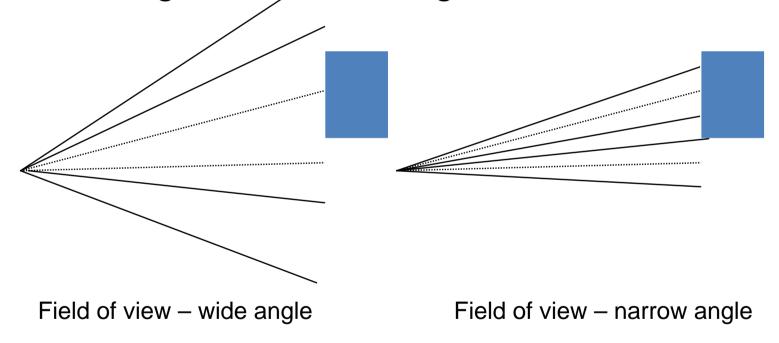


GPS inaccuracies

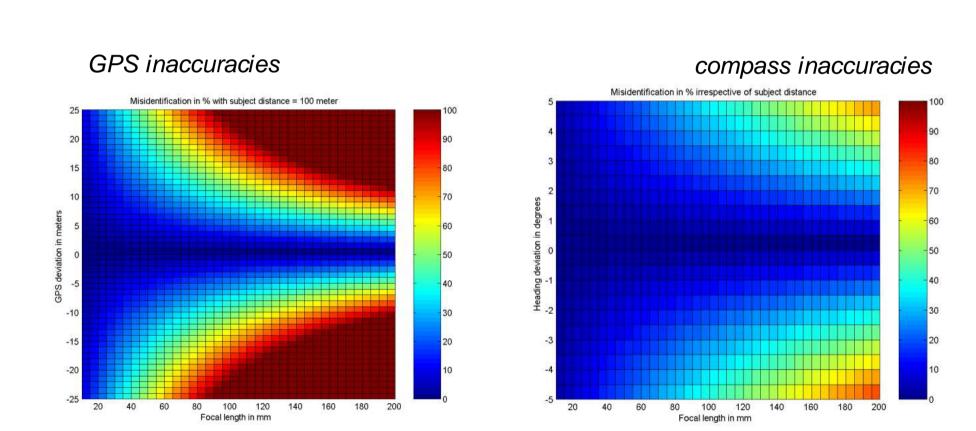


Compass inaccuracies

 Misidentification of objects increases with decreasing field of view angle



GPS and compass inaccuracies



Conclusion

"objects on a digital photo can be identified using the photo's full spatial metadata"

"methodology for object identification in digital imagery alternative from the existing methodologies"

"GIS technology and spatial data to create a virtual scene as output of perspective viewer services"

"problem of label placement in 3D Geo-Environments reduced to a 2D map labeling problem" More information:

www.projecttripod.org



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